Special types of first order equations - Linear Equations

Recommended reading from Zill's DEs with BVP-7e: Section 2.3 (pg 53-60): Examples 1 through 6.

Solve first order linear equations

A first order linear differential equation is an equation of the form

$$a_1(x)\frac{dy}{dx} + a_0(x)y = g(x)$$

Method of solution of a linear first order equation:

1. Rewrite the equation in standard form by dividing both sides by $a_1(x)$ to obtain

$$\frac{dy}{dx} + P(x)y = Q(x).$$

- 2. Find the integrating factor $I(x) = e^{\int P(x)dx}$.
- 3. Multiply both sides of the equation in Step 1 by I(x) to obtain

$$I(x)\frac{dy}{dx} + I(x)P(x)y = I(x)Q(x).$$

4. By the product rule, the left hand side of the above equation becomes $\frac{d}{dx}[I(x)y]$, i.e., the derivative with respect to x of the product of the integrating factor and y. So, the above equation becomes

$$\frac{d}{dx}\left[I(x)y\right] = I(x)Q(x).$$

5. Integrate both sides of the above equation with respect to x to obtain

$$I(x)y = \int I(x)Q(x)dx + C$$

6. Isolate y by dividing both sides of the above equation by I(x) to obtain a 1-parameter family of solutions.

Note: applying the formula $\frac{d}{dx} [e^u] = e^u \frac{du}{dx}$ with $u = \int P(x) dx$ we have

$$\frac{d}{dx}\left[I(x)\right] = \frac{d}{dx}\left[e^{\int P(x)dx}\right] = P(x)e^{\int P(x)dx} = P(x)I(x).$$

Applying the product rule $\frac{d}{dx}[uv] = u\frac{dv}{dx} + v\frac{du}{dx}$, we have

$$\frac{d}{dx}\left[I(x)y\right] = I(x)\frac{dy}{dx} + y\frac{d}{dx}\left[I(x)\right] = I(x)\frac{dy}{dx} + yP(x)I(x) = \text{left side of equation in Step 3.}$$

This is the justification for the claim at the beginning of Step 4.

In Step 5, when we integrate with respect to x the quantity $\frac{d}{dx}[I(x)y]$ on the left side, the $\frac{d}{dx}$ "goes away." This is because integration and differentiation are inverse operations of each other.

Note: It turns out that if P(x) and Q(x) are continuous on a common interval (a, b), then the 1-parameter family of solutions obtained by this method is the **true general solution** of the differential equation.

| Exa | mp | le 1 | : So | lve | a li | nea | r fi | \mathbf{rst} | orde | er e | qua | atio | n | | | | | | | | | | | | | | | |
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| Find | the | e gei | neral | l sol | utio | n of | $_{\mathrm{the}}$ | equ | atio | n an | nd d | leter | mine | $e 	ext{ the}$ | e lar | gest | int | erval | love | er w | hich | the | e sol | utio | n is | defi | ned. | |
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| Exa | \mathbf{mp} | le 2: | Solve | e an | IVI | 2 | | | | | | | | | | | | | | | | |
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Example 3: Discontinuous Forcing Term

| In this example we solv jump discontinuity. Consider the equation | | | | where the forci r | ng term $Q(x)$ i | is a function with a |
|---|--|------------------|---|--------------------------|------------------|-----------------------|
| | | $Q(x) = \bigg\{$ | $\begin{bmatrix} 1, & \text{if } 0 \le x \\ -1, & \text{if } x > \end{bmatrix}$ | ≤ 1 | | |
| 1. Find the general satisfied. | solution for $0 \le x \le$ | 1 and cho | ose the const | ant in the solut | ion so that the | initial condition is |
| 2. Find the general s part and the solu | $ \begin{array}{l} \text{solution for } x > 1 \text{ an} \\ \text{tion in this part agr} \end{array} $ | | | the solution so | that the solutio | n from the previous |
| Note: By "glueing" the equation except at | | | | er, we obtain a | continuous fur | nction that satisfies |

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